

The geodesic problem and Gromov-Hausdorff convergence

4.1 Metric derivative and geodesics in metric spaces

Let (E, d) be a metric space. Given a curve $\gamma: [a, b] \rightarrow E$, $\Gamma := \gamma([a, b])$

$$\text{Var}_a^b(\gamma) = \sup \left\{ \sum_{i=1}^{n-1} d(\gamma(t_i), \gamma(t_{i+1})) \mid a \leq t_1 < \dots < t_n \leq b \right\} \text{ for every pair } a, b \text{ with } a \leq a' \leq b' \leq b. \text{ (length)}$$

We say that γ is rectifiable if $\text{Var}(\gamma) < \infty$.

Rmk 4.1.1 If $\gamma: [a, b] \rightarrow E$ is a curve of finite variation and $l(t) = \text{Var}_a^t(\gamma)$, then

$$d(\gamma(t+h), \gamma(t)) \leq l(t+h) - l(t) \quad a \leq t \leq t+h \leq b$$

Therefore, if $l(t)$ is cts, then γ is also cts. If l is Lipschitz cts, so is γ .

$\text{Var}(\gamma) < \infty$ does not imply that γ is cts.

For $x, y \in E$, the problem of the geodesics joining x and y has two possible formulations.

$$\min \{ \text{Var}(\gamma) \mid \gamma \in \text{Lip}([a, b], E), \gamma(a) = x, \gamma(b) = y \}$$

Defⁿ 4.1.2 (Metric derivative) Given a curve $\gamma: [a, b] \rightarrow E$, we define the metric derivative of γ at the point $t \in (a, b)$ as the limit $\lim_{h \rightarrow 0} \frac{d(\gamma(t+h), \gamma(t))}{|h|}$ whenever it exists, we denote it by $|\dot{\gamma}(t)|$.

Eq. 4.1.3 $E = \mathbb{R}^n$. If γ is diffble at the pt t , then $|\dot{\gamma}(t)|$ is the euclidean norm of the derivative of γ at the pt t .

Eq. 4.1.4: If $E = \mathbb{R}^n$ with $\|\cdot\|$, d is induced by $\|\cdot\|$, then $|\dot{\gamma}(t_0)| = \left\| \frac{d\gamma}{dt}(t_0) \right\|$ at any pt t_0 where γ is diffble.

Thm 4.1.6. For each Lipschitz curve $\gamma: [a, b] \rightarrow E$ the metric derivative exists at \mathbb{L}^1 -almost every point in $[a, b]$.

Moreover, it holds that $\text{Var}(\gamma) = \int_a^b |\dot{\gamma}(t)| dt$.

Proof: Since γ is a cts function, $T = \gamma([a, b])$ is a cpt metric space, separable. $\{x_n\}$ be a seq. dense in T .

$$\varphi_n(t) := d(\gamma(t), x_n) \in \text{Lip}([a, b])$$

By the Rademacher thm, $\varphi_n(t)$ exists at \mathbb{L}^1 -a.e. $[a, b]$. Defining $m(t) := \sup |\varphi_n(t)|$.

We will prove that $|\dot{\gamma}(t)| = m(t)$ for \mathbb{L}^1 -a.e. t .

Observe that $x \mapsto d(x, x_n)$ is 1-Lipschitz. $\forall n$ we have

$$\lim_{h \rightarrow 0} \frac{d(\gamma(t+h), \gamma(t))}{|h|} \geq \lim_{h \rightarrow 0} \frac{|\varphi_n(t+h) - \varphi_n(t)|}{|h|} = |\dot{\varphi}_n(t)| \text{ holds for } \mathbb{L}^1\text{-a.e. } t \in [a, b].$$

taking the supremum wrt. n we obtain $\lim_{h \rightarrow 0} \frac{d(\gamma(t+h), \gamma(t))}{|h|} \geq m(t)$ for a.e. $t \in [a, b]$.

On the other hand, $d(\gamma(t), \gamma(s)) = \sup \{ |d(\gamma(t), x_n) - d(\gamma(s), x_n)| \} \leq \sup \int_s^t |\dot{\varphi}_n(\tau)| d\tau \leq \int_s^t m(\tau) d\tau$

$\text{Lip}(\varphi_n) \leq \text{Lip}(\gamma)$ (the Lip constant). Hence $m(t) \leq \text{Lip}(\gamma)$ and m is integrable over $[a, b]$. If $t \in (a, b)$

is a Lebesgue pt for m , $\lim_{h \rightarrow 0} \frac{d(\gamma(t+h), \gamma(t))}{|h|} \leq \lim_{h \rightarrow 0} \left| \frac{1}{h} \int_t^{t+h} m(\tau) d\tau \right| = m(t)$.

Since a.e. $t \in [a, b]$ is a Lebesgue pt

$$\text{Since } m(t) = |\dot{\gamma}(t)| \quad \sum_{i=1}^{n-1} d(\gamma(t_{i+1}), \gamma(t_i)) \leq \sum_{i=1}^{n-1} \int_{t_i}^{t_{i+1}} |\dot{\gamma}(\tau)| d\tau \leq \int_a^b |\dot{\gamma}(\tau)| d\tau \quad \forall a \leq t_1 < \dots < t_n \leq b.$$

Take the sup over partitions. $\text{Var}(\gamma) \leq \int_a^b |\dot{\gamma}(t)| dt$.

choose $\varepsilon > 0$, $h = \frac{b-a}{n}$, $t_i = a + ih$, $n \geq 2$ st $h \leq \varepsilon$.

$$\frac{1}{h} \int_a^{b-\varepsilon} d(\gamma(t+h), \gamma(t)) dt \leq \frac{1}{h} \int_0^{b-\varepsilon} d(\gamma(\tau+h), \gamma(\tau)) d\tau \leq \frac{1}{h} \int_0^h \text{Var}(\gamma) d\tau = \text{Var}(\gamma).$$

$$\int_a^{b-\varepsilon} |\dot{\gamma}(t)| dt = \int_a^{b-\varepsilon} \lim_{h \rightarrow 0} \frac{d(\gamma(t+h), \gamma(t))}{h} dt \leq \lim_{h \rightarrow 0} \frac{1}{h} \int_a^{b-\varepsilon} d(\gamma(t+h), \gamma(t)) dt \leq \text{Var}(\gamma)$$

$$\Rightarrow \int_a^b |\dot{\gamma}(t)| dt \leq \text{Var}(\gamma).$$

4.2 Reparametrization.

Thm 4.2.1 Suppose that $\gamma \in \text{Lip}([a, b], E)$, $L = \text{Var}(\gamma)$. Then there exists a Lipschitz curve $\tilde{\gamma}: [0, L] \rightarrow E$ s.t. $|\dot{\tilde{\gamma}}| = 1$ a.e. on $[0, L]$ and $\tilde{\gamma}([0, L]) = \gamma([a, b])$

Proof: WLOG assume $a=0$. Let $l(t) = \text{Var}_0^t(\gamma)$. Define $h(t) = \inf \{s \in [0, b] : l(s) = t\}$ $t \in [0, L]$. $h(0) = 0$, h is non decreasing, $h(L) \leq b$. Moreover, $l(h(t)) = t$ $\gamma(s) = \gamma(h(l(s)))$ for $t \in [0, L]$ and $s \in [0, b]$.

$$\begin{aligned} \text{Observe that } l(h(s)) \leq s \text{ and } d(\gamma(h(l(s))), \gamma(s)) &\leq \text{Var}_{h(l(s))}^s(\gamma) \\ &= l(s) - l(h(l(s))) \\ &= l(s) - l(s) = 0. \end{aligned}$$

Define $\tilde{\gamma}(t) := \gamma(h(t))$ $t \in [0, L]$. $\text{Var}_0^t(\tilde{\gamma}) = t$ $\forall t \in [0, L]$.

$$\begin{aligned} \text{If } 0 \leq t_1 \leq \dots \leq t_n \leq L, \text{ letting } s_i = h(t_i), \sum_{i=1}^{n-1} d(\tilde{\gamma}(t_{i+1}), \tilde{\gamma}(t_i)) &= \sum_{i=1}^{n-1} d(\gamma(s_{i+1}), \gamma(s_i)) \\ &\leq \text{Var}_0^{s_n}(\gamma) = l(s_n) = t_n \leq L. \end{aligned}$$

On the other hand, for $t \in [0, L]$ and $\epsilon > 0$, $\exists 0 = s_1 \leq \dots \leq s_n = h(t)$ s.t.

$$\begin{aligned} l(h(t)) &\leq \epsilon + \sum_{i=1}^{n-1} d(\gamma(s_{i+1}), \gamma(s_i)) \\ \Rightarrow t &\leq \epsilon + \sum_{i=1}^{n-1} d(\gamma(h(l(s_{i+1}))), \gamma(h(l(s_i)))) \\ &= \epsilon + \sum_{i=1}^{n-1} d(\tilde{\gamma}(l(s_{i+1})), \tilde{\gamma}(l(s_i))) \\ &\leq \epsilon + \text{Var}_{l(s_1)}^{l(s_n)}(\tilde{\gamma}) \\ &= \epsilon + \text{Var}_0^{l(h(t))}(\tilde{\gamma}) \\ &= \epsilon + \text{Var}_0^t(\tilde{\gamma}) \end{aligned} \quad \tilde{\gamma} \text{ is } 1\text{-Lipschitz.}$$

Finally, $t = \text{Var}_0^t(\tilde{\gamma}) = \int_0^t |\dot{\tilde{\gamma}}(\tau)| d\tau$ $\forall t \in [0, L]$.

differentiating w.r.t. t , $|\dot{\tilde{\gamma}}(t)| = 1$ for a.e. t .

Defⁿ: We say γ is rectifiable if $l(\gamma) := \sup \sum_{i=0}^{N-1} d(\gamma(t_i), \gamma(t_{i+1})) < \infty$
 where sup is over all finite collections $a=t_0 < t_1 < \dots < t_N = b$

Thm: If γ is rectifiable then there exists a curve $\alpha: [0, l(\gamma)] \rightarrow X$

st. i) $\forall s \in [0, l(\gamma)]$, $l(\alpha|_{[0,s]}) = s$

ii) In particular, α is 1-Lipschitz

α is called the arclength parametrization.

$$d(\alpha(s), \alpha(s')) \leq l(\gamma|_{[s,s']}) = |s - s'|$$

ii) $\gamma(s) = \alpha(h(s))$ for some increasing $h: [a,b] \rightarrow [0, l(\gamma)]$

Ex: Take $f: [0,1] \rightarrow [0,1]$ be the Cantor-Vitali function. Let $\gamma(t) = (t, f(t))$

$$[0,1] \rightarrow \mathbb{R}^2 = X$$

γ is rectifiable, but it is not Lipschitz.

Ex Find the right h - compute it!

Defⁿ: We say $u: X \rightarrow \mathbb{R}$ is abs cts on a rectifiable curve γ if

$$u \circ \alpha: [0, l(\gamma)] \rightarrow \mathbb{R}$$

is abs cts where α is the arclength parametrization of γ .

Ex: Let $u: \mathbb{R}^n \rightarrow \mathbb{R}$ be C^1 , $\gamma: [a,b] \rightarrow \mathbb{R}^n$ C^1 .

$$u \circ \gamma: [a,b] \rightarrow \mathbb{R} \text{ is } C^1 \quad (u \circ \gamma)'(t) = \nabla u(\gamma(t)) \cdot \gamma'(t)$$

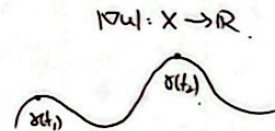
It follows that $(u \circ \gamma)(b) - (u \circ \gamma)(a) = \int_a^b \langle \nabla u(\gamma(t)), \gamma'(t) \rangle dt$ not on X .

$$|u(\gamma(t_2)) - u(\gamma(t_1))| \leq \int_{t_1}^{t_2} |\nabla u(\gamma(t))| |\gamma'(t)| dt$$

If γ is arclength parametrized, then,

$$|u(\gamma(t_2)) - u(\gamma(t_1))| \leq \int_{t_1}^{t_2} |\nabla u(\gamma(t))| dt$$

object on $X = \mathbb{R}^n$.



Recall: $f: [a,b] \rightarrow \mathbb{R}$ is abs cts iff there is $g \in L^1([a,b])$ s.t. $f(x) = f(a) + \int_a^x g(t) dt$.

Lemma: Suppose there exists some function $p \geq 0$ on $[a,b]$ s.t. $\forall t_1, t_2$, $p \in L^1([a,b])$.

$$|u(\gamma(t_2)) - u(\gamma(t_1))| \leq \int_{t_1}^{t_2} p(t) dt$$

then $u \circ \gamma$ is absolutely continuous, i.e. u is AC on γ .

Proof: Any collection of disjoint (t_j, t_{j+1}) satisfy $* = \sum_j |u(\gamma(t_{j+1})) - u(\gamma(t_j))| \leq \sum_j \int_{t_j}^{t_{j+1}} p(t) dt$
 $= \int_{\cup_j (t_j, t_{j+1})} p(t) dt$.

By AC of \int , $\forall \epsilon > 0$, $\exists \delta > 0$ s.t. $|A| < \delta \Rightarrow \int_A p(t) dt < \epsilon$.

so if $\sum_j |t_{j+1} - t_j| < \delta \Rightarrow * < \epsilon$.

For $u: X \rightarrow \mathbb{R}$, we will seek $p \geq 0$ s.t. $|u(\gamma(t_2)) - u(\gamma(t_1))| \leq \int_{t_1}^{t_2} p(s) ds$

If such p belongs to $L^1([a,b])$ then u will be AC on γ .

In $X = \mathbb{R}^n$ with $u \in C^1(\mathbb{R}^n)$, $|\nabla u(\gamma(t))| = p(t)$ is the right p .

Benamou - Brenier Formulation.

Let's consider a density $p(t, x)$ $x \in \mathbb{R}^n$ $0 \leq t \leq 1$

We want $p(0, x) = f(x)$ $p(1, x) = g(x)$

Introduce velocity field $v(t, x)$.

Describe a mass-preserving flow via the continuity eqt.

$$p_t + \nabla \cdot (vp) = 0.$$

Introduce Lagrangian coordinates $X(t, x)$ to "follow" the particle through the flow.

$$\begin{cases} \frac{\partial X}{\partial t}(t, x) = v(t, X(t, x)) \\ X(0, x) = x \end{cases}$$

Mass in E at $t=0$ = Mass in $X(t, E)$ at time t .

$$\Rightarrow \int_E f(x) dx = \int_{X(t, E)} p(t, x) dx. \quad \forall 0 \leq t \leq 1.$$

This is the statement $X(t, \cdot) \# f = p(t, \cdot)$
and

$$X(1, \cdot) \# f = g$$

$$\begin{aligned} W_2^2(f, g) &\leq \int_{\mathbb{R}^n} f(x) |X(1, x) - x|^2 dx \\ &= \int_{\mathbb{R}^n} f(x) |X(1, x) - X(0, x)|^2 dx \\ &= \int_{\mathbb{R}^n} f(x) \left| \int_0^1 \frac{\partial X}{\partial t}(t, x) dt \right|^2 dx \\ &\leq \int_{\mathbb{R}^n} \int_0^1 f(x) \left| \frac{\partial X}{\partial t}(t, x) \right|^2 dt dx \\ &= \int_0^1 \int_{\mathbb{R}^n} f(x) |v(t, X(t, x))|^2 dx dt. \end{aligned}$$

Fix t Define $S(x) = X(t, x)$.

$$S \# f = p(t, x)$$

$$\varphi(y) = |v(t, y)|^2$$

$$\int_{\mathbb{R}^n} f(x) |v(t, X(t, x))|^2 dx$$

$$= \int_{\mathbb{R}^n} f(x) \varphi(S(x)) dx.$$

$$= \int_{\mathbb{R}^n} p(t, y) \varphi(y) dy. \quad (\text{push forward})$$

$$= \int_{\mathbb{R}^n} p(t, y) |v(t, y)|^2 dy.$$

$$W_2^2(f, g) \leq \int_0^1 \int_{\mathbb{R}^n} p(t, x) |v(t, x)|^2 dx dt$$

$$\forall p, v \text{ satisfying } \begin{cases} p_t + \nabla \cdot (p v) = 0 \\ p(0, x) = f(x) \\ p(1, x) = g(x) \end{cases}$$

Can we achieve equality?

Need $X(1, x) = T(x)$ the optimal map from f to g .

$$\text{Need } \left| \int_0^1 \frac{\partial X}{\partial t}(t, x) dt \right|^2 = \int_0^1 \left| \frac{\partial X}{\partial t}(t, x) \right|^2 dt$$

This holds if $\frac{\partial X}{\partial t}(t, x) = u(x)$ is constant in time.

Recall: $X(0, x) = x$.

$$\Rightarrow X(t, x) = x + u(x)t$$

$$X(1, x) = x + u(x) = T(x)$$

$$\Rightarrow u(x) = T(x) - x$$

$$X(t, x) = x + (T(x) - x)t = x(1-t) + tT(x)$$

Our velocity field should satisfy $v(t, X(t, x)) = u(x) = T(x) - x = (T - I)(x)$.

$$\text{Let } y = X(t, x) = [(1-t)I + tT](x)$$

$$\Rightarrow v(t, y) = (T - I)[(1-t)I + tT]^{-1}(y)$$

achieves the optimum. if (f, g) are nice, else do "smoothed" approximations.

$$W_2^2(f, g) = \inf_{p, v} \int_0^1 \int_{\mathbb{R}^n} p(t, x) |v(t, x)|^2 dx dt \quad \text{s.t.} \quad \begin{cases} p_t + \nabla \cdot (p v) = 0 \\ p(0, x) = f(x) \\ p(1, x) = g(x) \end{cases} \quad \text{BB formulation.}$$

$$\text{Eg. } \min f(x) \text{ s.t. } Ax = b. \quad L(x, \lambda) = f(x) + \lambda(Ax - b)$$

$$\min \left\{ f(x) + \sup_{\lambda} \lambda(Ax - b) \right\} \quad \text{seek saddle pts of this.}$$

Let $\varphi(t, x)$ be the Lagrange multiplier.

$$\text{IBP } \int_0^1 \int_{\mathbb{R}^n} (p_t + \nabla \cdot (p v)) \varphi dx dt = \int_{\mathbb{R}^n} (g(x)\varphi(x, 1) - f(x)\varphi(x, 0)) dx - \int_0^1 \int_{\mathbb{R}^n} (p_t \varphi + p v \cdot \nabla \varphi) dx dt$$

$$\text{Lagrangian } L = \int_0^1 \int_{\mathbb{R}^n} \left(\frac{p|v|^2}{2} - p p_t - p v \cdot \nabla \varphi \right) dx dt + \underbrace{\int_{\mathbb{R}^n} (g(x)\varphi(x, 1) - f(x)\varphi(x, 0)) dx}_{G(\varphi)}$$

$$\text{Letting } m = pv \quad L(\varphi, p, m) = \int_0^1 \int_{\mathbb{R}^n} \left(\frac{m^2}{2p} - p p_t - m \cdot \nabla \varphi \right) dx dt + G(\varphi)$$

Want to solve $\inf_{p, m} \sup_{\varphi} L(\varphi, p, m)$.

$$\text{Let } h(p, m) = \frac{m^2}{2p} \quad \text{Claim: } h(p, m) = \sup_{(a, b) \in K} (ap + bm) \quad \text{to express the quadratic in terms of linear}$$

$$K = \{(a, b) \in \mathbb{R}^2 \times \mathbb{R}^n : a + \frac{|b|^2}{2} \leq 0\}$$

Proof Let (a^*, b^*) be the sup. Since $p > 0$, a^* as big as possible. $\Rightarrow a^* = -\frac{|b^*|^2}{2}$

$$\sup_{(a, b) \in K} (ap + bm) = \sup_{(a, b) \in \mathbb{R}^2 \times \mathbb{R}^n} \left(-\frac{p|b|^2}{2} + b \cdot m \right) \Rightarrow \text{set gradient to 0. } -pb + m = 0 \Rightarrow b^* = \frac{m}{p}$$

$$\sup_{(a, b) \in K} (ap + bm) = -\frac{m^2}{2p} + \frac{m^2}{p} = \frac{m^2}{2p} = h(p, m)$$

Saddle pt problem is $\inf_{p,m} \sup_{\varphi \in C^1(a,b) \times C^1(c,d)} \int_0^1 \int_{\mathbb{R}^n} (a\varphi_t + b \cdot m - p\varphi_t - m \cdot \nabla \varphi) dx dt + G(\varphi)$.

$$= \inf_{p,m} \sup_{\varphi \in C^1(a,b) \times C^1(c,d)} \int_0^1 \int_{\mathbb{R}^n} [(a-\varphi_t)p + (b-\nabla \varphi) \cdot m] dx dt + G(\varphi).$$

Let $r = \begin{pmatrix} p \\ m \end{pmatrix}$, $\delta = \begin{pmatrix} a \\ b \end{pmatrix}$, $\nabla_{t,x} \varphi = \begin{pmatrix} \varphi_t \\ \nabla \varphi \end{pmatrix}$.

$$\Rightarrow \inf_r \sup_{\varphi, \delta \in K} \langle \delta - \nabla_{t,x} \varphi, r \rangle + G(\varphi).$$

Let $\tau > 0$ be small to regularize the max

$$\inf_r \sup_{\varphi, \delta \in K} \langle \delta - \nabla_{t,x} \varphi, r \rangle + G(\varphi) - \frac{\tau}{2} \|\delta - \nabla_{t,x} \varphi\|^2.$$

optimize these 3 unknowns ~~independently~~ independently

Given r_k, δ_k , $\varphi_{k+1} = \operatorname{argmax}_{\varphi} - \langle \nabla_{t,x} \varphi, r \rangle + G(\varphi) - \frac{\tau}{2} \|\delta - \nabla_{t,x} \varphi\|^2$.
quadratic, unconstrained, ez.

Computing 1st variation \Rightarrow Poisson equation with Neumann BC (homogeneous in space & non-homogeneous in time)

$$\Delta_{t,x} \varphi_{k+1} = \nabla \cdot (\delta_k - \frac{r_k}{\tau}).$$

Given r_k, φ_{k+1} , optimize for δ_{k+1} .

$$\delta_{k+1} = \operatorname{argmax}_{\delta \in K} \langle \delta, r \rangle - \frac{\tau}{2} \|\delta - \nabla_{t,x} \varphi\|^2.$$

Do this pointwise (quadratic)

Given $\varphi_{k+1}, \delta_{k+1}$, we do gradient descent in r .

$$r_{k+1} = r_k - \tau (\delta_{k+1} - \nabla_{t,x} \varphi_{k+1}). \text{ Iterate.}$$

JKO flows

Let $F: \mathbb{R}^n \rightarrow \mathbb{R}$ be convex we want to minimize $F(x)$.

$$\text{Gradient flow: } \begin{cases} x'(t) = -\nabla F(x(t)) \\ x(0) = x_0 \end{cases}$$

Discretize in time via Backward Euler.

$$\frac{x^{n+1} - x^n}{\tau} = -\nabla F(x^{n+1})$$

$$\Rightarrow \frac{x^{n+1} - x^n}{\tau} + \nabla F(x^{n+1}) = 0$$

$$\Rightarrow \nabla \left(\frac{|x - x^n|^2}{2\tau} + F(x) \right) \Big|_{x=x^{n+1}} = 0$$

$$\Rightarrow x^{n+1} \in \operatorname{argmin} \left\{ \frac{|x - x^n|^2}{2\tau} + F(x) \right\}$$

Can define a scheme like this on a metric space (X, d) .

Let $F: X \rightarrow \mathbb{R}$ be lsc and bounded below.

$$\text{Define } x_{\tau}^{n+1} \in \operatorname{argmin} \left\{ F(x) + \frac{d(x, x_{\tau}^n)^2}{2\tau} \right\}$$

$$\text{Interpolate to all } t \quad x_{\tau}(t) = x_{\tau}^n \text{ if } t \in (n\tau, (n+1)\tau]$$

Study limit as $\tau \rightarrow 0$.

Consider $F: P(\Omega) \rightarrow \mathbb{R}$ $d = W_2$. Ω is compact, F lsc bounded below.

We previously used the continuity eq $\rho + \nabla \cdot (\rho v) = 0$ to "flow" densities.

Goal: Find velocity field v st. this flow agrees with $\lim_{\tau \rightarrow 0} x_{\tau}(t)$.

Investigate optimality condition in the JKO scheme.

We need to compute the 1st variation

We need to perturb $p \in P(\Omega)$ to $p + \varepsilon \chi$. Need $p + \varepsilon \chi \in P(\Omega)$ st. $F(p + \varepsilon \chi)$ is well-defined

Restrict to χ st. $\sigma = p + \varepsilon \chi \in P(\Omega) \forall$ small ε .

$$\Rightarrow p + \varepsilon \chi = \sigma + \varepsilon(\sigma - p)$$

$$= p(1 - \varepsilon) + \varepsilon \sigma \in P(\Omega) \text{ as long as } p, \sigma \in P(\Omega)$$

$$\forall \sigma \in P(\Omega) \cap L^{\infty}(\Omega)$$

The first variation of F , $\frac{\delta F}{\delta p}(p)$ is st. $\frac{d}{d\varepsilon} F(p + \varepsilon \chi) \Big|_{\varepsilon=0} = \int \frac{\delta F}{\delta p}(p) \chi(x) dx$. $\forall \chi = \sigma - p$
 $\sigma \in P(\Omega) \cap L^{\infty}(\Omega)$

$$\int \left(\frac{\delta F}{\delta p} + c \right) \chi(x) dx = \int \frac{\delta F}{\delta p} \chi(x) dx + c \int \chi(x) dx = 0$$

The 1st variation is defined uniquely only up to additive constants.

$$\text{Come back to } G(p) = F(p) + \frac{W_2(p, p^n)^2}{2\tau}$$

$$\text{We need } \frac{\delta G}{\delta p}(p) = \frac{\delta F}{\delta p}(p) + \frac{1}{2\tau} \frac{\delta W_2^2}{\delta p}(p, p^n)$$

Use the dual formulation: $W_2^2(f, g) = 2 \inf_{\pi \in \Pi(f, g)} \int \frac{|x-y|^2}{2} d\pi(x, y)$.

$$= 2 \max_{u, v} \left\{ \int u f dx + \int v g dy \mid u(x) + v(y) \leq \frac{1}{2} |x-y|^2 \right\}$$

$$= 2 \max_u \left\{ \int u f dx + \int u^c g dy \right\}$$

$$\frac{d}{d\varepsilon} W_2^2(f + \varepsilon \chi, g) \Big|_{\varepsilon=0} = 2 \frac{d}{d\varepsilon} \max_u \left\{ \int u(f + \varepsilon \chi) dx + \int u^c g dy \right\} \Big|_{\varepsilon=0}$$

$$= 2 \int u^* \chi dx \quad \text{where } u^* \text{ achieves the max.}$$

(potential associated with the cost $\frac{1}{2} |x-y|^2$.)

When we do OT, the optimal map is $T(x) = x - \nabla u^*(x)$.

$$= x - (\nabla h)^{-1}(\nabla u^*(x)) \quad \text{where } h(z) = \frac{1}{2} |z|^2.$$

$$\Rightarrow \frac{\delta W_2^2}{\delta p}(p, p_T^n) = 2u^*$$

$T(x) = x - \nabla u^*(x)$ is the optimal map from p to p_T^n .

The JKO scheme is $p_T^{n+1} = \operatorname{argmin} \left\{ F(p) + \frac{W_2^2(p, p_T^n)}{2\tau} \right\}$

$$= \operatorname{argmin} G(p).$$

$$\Rightarrow \frac{\delta G}{\delta p}(p_T^{n+1}) + C = 0.$$

$$\Rightarrow \frac{\delta F}{\delta p}(p_T^{n+1}) + \frac{u^*}{\tau} = \text{constant}.$$

$$\Rightarrow 0 = \nabla \left(\frac{\delta F}{\delta p} \right) + \frac{\nabla u^*}{\tau}$$

$$= \nabla \left(\frac{\delta F}{\delta p} \right) + \frac{x - T(x)}{\tau}$$

$$\Rightarrow \frac{T(x) - x}{\tau} = \nabla \left(\frac{\delta F}{\delta p} \right)$$

velocity!

of a flow from p_T^{n+1} to p_T^n .

The flow we want should have velocity $v(x) := -\left(\frac{T(x) - x}{\tau} \right)$

This is the velocity associated with our time discrete scheme.

If everything works out as $\tau \rightarrow 0$, we expect our JKO scheme to limit to this flow

$$p_t + \nabla \cdot (p v) = 0 \quad \text{or} \quad p_t - \nabla \cdot \left(p \frac{\delta F}{\delta p} \right) = 0.$$

This is the PDE associated with gradient flows of F in the W_2 metric.

Eg. $F(p) = \int p \log p dx$. We want a flow that maximizes entropy.

$$\frac{d}{d\varepsilon} F(p + \varepsilon \chi) \Big|_{\varepsilon=0} = \frac{d}{d\varepsilon} \int (p + \varepsilon \chi) \log(p + \varepsilon \chi) dx \Big|_{\varepsilon=0} = \int (\chi \log p + \chi) dx. \quad \Rightarrow \frac{\delta F}{\delta p} = \log p + 1.$$

$$\nabla \left(\frac{\delta F}{\delta p} \right) = \nabla (\log p + 1) = \frac{1}{p} \nabla p. \quad \Rightarrow \text{the GF is } 0 = p_t - \nabla \cdot (p \cdot \frac{1}{p} \nabla p) = \cancel{p_t - \nabla \cdot (\nabla p)}$$

$$= p_t - \nabla \cdot (\nabla p)$$

$$= p_t - \Delta p.$$

$$\Rightarrow p_t = \Delta p \text{ (heat equation).}$$

$$\text{Eg. } F(p) = \int p \log p \, dx + \int v(x) p \, dx$$

$$\Rightarrow p_t - \Delta p - \nabla \cdot (p \nabla v) = 0 \quad \text{Fokker-Planck}$$

$$\text{Eg. } F(p) = \frac{1}{m-1} \int p^m \, dx$$

$$\Rightarrow p_t - \Delta(p^m) = 0 \quad \text{porous medium}$$

$$\text{Eg. } F(p) = \int p \log p - \frac{1}{2} \int |\nabla u_p|^2 \quad \text{where } -\Delta u_p = p$$

$$\Rightarrow \begin{cases} p_t + \nabla \cdot (p \nabla u) - \Delta p = 0 \\ -\Delta u = p \end{cases} \quad (\text{Keller-Segel, chemotaxis})$$

$$\text{E. } F(p) = \frac{1}{2} \iint w(x-y) \, dp(x) \, dp(y)$$

$$\Rightarrow p_t - \nabla \cdot (p(\nabla w) \cdot p) = 0 \quad (\text{aggregation model})$$

Otd's calculus

By BB formula $\|u\|_{P_1}^2 = \inf_{P_1, v} \left\{ \int_{\Omega} |\nabla u|^2 P_1 dx \right\} \cdot \text{normal } u \cdot \nu|_{\partial\Omega} = 0, P_0 = \bar{P}_0, P_1 = \bar{P}_1$

$$= \inf_{P_1} \left\{ \int_{\Omega} |\nabla u|^2 P_1 dx \right\} \cdot \text{normal } u \cdot \nu|_{\partial\Omega} = 0, P_0 = \bar{P}_0, P_1 = \bar{P}_1$$

$$= \inf_{P_1} \left\{ \int_{\Omega} |\nabla u|^2 P_1 dx \mid \text{div}(u P_1) = -\Delta P_1, \nu \cdot n|_{\partial\Omega} = 0 \right\} \cdot \text{normal } u \cdot \nu|_{\partial\Omega} = 0, P_0 = \bar{P}_0, P_1 = \bar{P}_1$$

$$\| \Delta P_1 \|_{P_1}^2$$

In analogy with the Riemann distance

$$\| \Delta P_1 \|_{P_1}^2 = \inf_{P_1} \left\{ \int_{\Omega} |\nabla u|^2 P_1 dx \mid \text{div}(u P_1) = -\Delta P_1, \nu \cdot n|_{\partial\Omega} = 0 \right\}$$

$$\Rightarrow \| \Delta P_1 \|_{P_1}^2 = \inf_{P_1} \left\{ \int_{\Omega} |\Delta P_1|^2 P_1 dx \mid P_0 = \bar{P}_0, P_1 = \bar{P}_1 \right\}$$

We want the u that realizes the infimum.

Hence, given $P_1, \Delta P_1$, let u be a minimizer, w be a vector field st. $\text{div}(w) = 0$ and $w \cdot n|_{\partial\Omega} = 0$.

$$\forall \epsilon > 0 \quad \text{div}((u + \epsilon \frac{w}{P_1}) P_1) = -\Delta P_1$$

Thus $u + \epsilon \frac{w}{P_1}$ is an admissible vector field.

$$\int_{\Omega} |\nabla u|^2 P_1 dx \leq \int_{\Omega} |\nabla (u + \epsilon \frac{w}{P_1})|^2 P_1 dx = \int_{\Omega} |\nabla u|^2 P_1 dx + 2\epsilon \int_{\Omega} \langle \nabla u, \nabla w \rangle P_1 dx + \epsilon^2 \int_{\Omega} \frac{|\nabla w|^2}{P_1} dx$$

$$\text{Divide by } \epsilon \text{ and let } \epsilon \rightarrow 0 \text{ yields } \int_{\Omega} \langle \nabla u, \nabla w \rangle P_1 dx = 0 \quad \forall w \text{ st. } \text{div}(w) = 0 \text{ and } w \cdot n|_{\partial\Omega} = 0$$

By the Helmholtz decomp $u \in \{ u \mid \text{div}(u) = 0, u \cdot n|_{\partial\Omega} = 0 \} = \{ \nabla \phi \mid \phi \in C^\infty \rightarrow \mathbb{R} \}$

$\Rightarrow \exists$ function ψ_1 st. $u = \nabla \psi_1$. Since $\text{div}(u P_1) = -\Delta P_1$ and $u \cdot n|_{\partial\Omega} = 0$, then ψ_1 is a sol. of

$$\begin{cases} \text{div}(P_1 \nabla \psi_1) = -\Delta P_1 & \text{in } \Omega \\ \frac{\partial \psi_1}{\partial n} = 0 & \text{on } \partial\Omega \end{cases}$$

If P_1 is 'nice', this is the uniformly elliptic equation with Neumann boundary conditions for ψ_1 , the solution ψ_1 is unique up to a constant. So one can define

$$\| \Delta P_1 \|_{P_1}^2 = \int_{\Omega} |\nabla \psi_1|^2 P_1 dx \quad \psi_1 \text{ solves the DE.}$$

More generally, given $P_1 \in C^\infty(\Omega)$ $h: \Omega \rightarrow \mathbb{R}$ st. $\int_{\Omega} h = 0$

this is needed for the solvability of the DE.

$$\text{Rmk. } \begin{cases} \int_{\Omega} h dx = \int_{\Omega} \text{div}(P_1 \nabla \psi) dx = \int_{\partial\Omega} \frac{\partial \psi}{\partial n} P_1 = 0 \\ \text{wherever } P_1 \text{ is a cure of prob.} \\ \int_{\Omega} \Delta P_1 dx = \frac{d}{dt} \int_{\Omega} P_1 dx = \frac{d}{dt} 1 = 0 \end{cases}$$

$$\text{We can define } \| h \|_{P_1}^2 = \int_{\Omega} |\nabla \psi|^2 P_1 dx \quad \text{where } \begin{cases} \text{div}(P_1 \nabla \psi) = -h & \text{in } \Omega \\ \frac{\partial \psi}{\partial n} = 0 & \text{on } \partial\Omega \end{cases}$$

Construction of norm is done.

(1)

Defⁿ Given two functions $h_1, h_2: \Omega \rightarrow \mathbb{R}$ with $\int_{\Omega} h_1 = 0, \int_{\Omega} h_2 = 0$.

$$\langle h_1, h_2 \rangle := \int_{\Omega} \nabla h_1 \cdot \nabla h_2 \, p \, dx \quad \text{where } \begin{cases} \operatorname{div}(p \nabla h_i) = -h_i & \text{in } \Omega \\ p \frac{\partial h_i}{\partial n} = 0 & \text{on } \partial \Omega \end{cases}$$

Defⁿ Given a functional $J \in \mathcal{B}_2(\Omega)^*$ (dual), its gradient w.r.t. the Wasserstein scalar product at $\bar{p} \in \mathcal{B}_2(\Omega)$ is the unique function $\operatorname{grad}_{W_2} J[\bar{p}]$ st.

$$\frac{d}{d\varepsilon} J[\bar{p}_\varepsilon] \Big|_{\varepsilon=0} = \langle \operatorname{grad}_{W_2} J[\bar{p}], \frac{\partial \bar{p}_\varepsilon}{\partial \varepsilon} \Big|_{\varepsilon=0} \rangle_{\bar{p}}$$

\forall smooth curve $\bar{p}_\varepsilon = (\varepsilon_0, \varepsilon_0) \rightarrow \mathcal{P}(\Omega)$ with $\bar{p}_0 = \bar{p}$.

What are explicit formula? Given $J \in \mathcal{B}_2(\Omega)^*$ and $\bar{p} \in \mathcal{B}_2(\Omega)$.

Denote by $\frac{\delta J[\bar{p}]}{\delta p}$ its first L^2 variation

$$\frac{d}{d\varepsilon} \int_{\Omega} J[\bar{p}_\varepsilon] = \int_{\Omega} \frac{\delta J[\bar{p}]}{\delta p}(x) \frac{\partial \bar{p}_\varepsilon(x)}{\partial \varepsilon} \Big|_{\varepsilon=0} \, dx \quad \forall \text{ smooth } \bar{p}_\varepsilon = (\varepsilon_0, \varepsilon_0) \rightarrow \mathcal{P}_2(\Omega) \text{ st } \bar{p}_0 = \bar{p}$$

Then by the defⁿ of Wasserstein gradient,

$$\langle \operatorname{grad}_{W_2} J[\bar{p}], \frac{\partial \bar{p}_\varepsilon}{\partial \varepsilon} \Big|_{\varepsilon=0} \rangle_{\bar{p}} = \int_{\Omega} \frac{\delta J[\bar{p}]}{\delta p} \frac{\partial \bar{p}_\varepsilon}{\partial \varepsilon} \Big|_{\varepsilon=0} \, dx$$

Thus denoting by ψ the solution of $\operatorname{div}(\nabla \psi \bar{p}) = -\frac{\partial \bar{p}_\varepsilon}{\partial \varepsilon} \Big|_{\varepsilon=0}$ with zero Neumann boundary conditions,

$$\begin{aligned} \langle \operatorname{grad}_{W_2} J[\bar{p}], \frac{\partial \bar{p}_\varepsilon}{\partial \varepsilon} \Big|_{\varepsilon=0} \rangle_{\bar{p}} &= - \int_{\Omega} \frac{\delta J[\bar{p}]}{\delta p} \operatorname{div}(\nabla \psi \bar{p}) \, dx \\ &= \int_{\Omega} \nabla \frac{\delta J[\bar{p}]}{\delta p} \cdot \nabla \psi \bar{p} \, dx \end{aligned}$$

$$\text{if } \bar{p} \frac{\partial}{\partial n} \left(\frac{\delta J[\bar{p}]}{\delta p} \right) = 0 \text{ on } \partial \Omega, \quad \operatorname{grad}_{W_2} J[\bar{p}] = - \operatorname{div} \left(\nabla \left(\frac{\delta J[\bar{p}]}{\delta p} \right) \bar{p} \right)$$

Now we give an e.g. that the Wasserstein gradient doesn't exist if $\bar{p} \frac{\partial}{\partial n} \left(\frac{\delta J[\bar{p}]}{\delta p} \right) \neq 0$ on $\partial \Omega$.

If $J[p] = \int_{\Omega} U(p(x)) \, dx \quad U: \mathbb{R} \rightarrow \mathbb{R}, \quad \forall$ smooth variation $\varepsilon_1 \rightarrow \varepsilon_2$

$$\frac{d}{d\varepsilon} \int_{\Omega} U(p_\varepsilon(x)) \, dx = \int_{\Omega} U'(p_\varepsilon(x)) \frac{\partial p_\varepsilon(x)}{\partial \varepsilon} \Big|_{\varepsilon=0} \, dx$$

the L^2 -variation of $J[p]$ at $\bar{p} \in \mathcal{B}_2(\Omega)$ is given by $\frac{\delta J[\bar{p}]}{\delta p}(x) = U'(\bar{p}(x))$

$$\Rightarrow \operatorname{grad}_{W_2} J[\bar{p}] = - \operatorname{div}(\bar{p} \nabla [U'(\bar{p})]) = - \operatorname{div}(\bar{p} U''(\bar{p}) \nabla \bar{p}) \quad \text{if } \bar{p} U''(\bar{p}) \frac{\partial \bar{p}}{\partial n} = 0 \text{ on } \partial \Omega$$

In the special case $U(s) = s \log(s), \quad U''(s) = \frac{1}{s} \Rightarrow \operatorname{grad}_{W_2} J[\bar{p}] = -\Delta \bar{p}$ if $\frac{\partial \bar{p}}{\partial n} = 0$ on $\partial \Omega$

$$\text{if } U(s) = \frac{s^m}{m-1} \quad \exists m \neq 1, \quad \operatorname{grad}_{W_2} J[\bar{p}] = - \operatorname{div}(\bar{p}^m \bar{p}^{m-2} \nabla \bar{p}) = -\Delta(\bar{p}^m)$$

$$\text{if } \frac{\partial \bar{p}^m}{\partial n} = 0 \text{ on } \partial \Omega$$

(Cont)

If $J[p] = \int_{\Omega} p(x) V(x) dx$ with $V: \Omega \rightarrow \mathbb{R}$ its first L^2 -variation at $\bar{p} \in P_2(\Omega)$ is

$$\frac{\delta J[\bar{p}]}{\delta p}(x) = V(x)$$

Therefore the Wasserstein gradient of J is $\text{grad}_{W_2} J[\bar{p}] = -\text{div}(\nabla V \bar{p})$ given $\bar{p} \partial_n V = 0$ on $\partial\Omega$.

If $J[p] = \frac{1}{2} \iint p(x) p(y) W(x,y) dx dy$ $W: \mathbb{R}^d \rightarrow \mathbb{R}$ s.t. $W(z) = W(-z)$,

$$\frac{\delta J[\bar{p}]}{\delta p}(x) = W * \bar{p}(x) = \int_{\Omega} W(x-y) p(y) dy$$

$$\Rightarrow \text{grad}_{W_2} J[\bar{p}] = -\text{div}((\nabla W * \bar{p}) \bar{p}) \quad \text{given } \bar{p} \partial_n \frac{\delta J[\bar{p}]}{\delta p} = 0 \text{ on } \partial\Omega$$

Defⁿ: Given a functional $J: P_2(\Omega) \rightarrow \mathbb{R}$, $p: [0, T] \rightarrow P_2(\Omega)$ is a gradient

flow of J w.r.t. W_2 and with starting point \bar{p}_0 if

$$\begin{cases} \partial_t p = -\text{grad}_{W_2} J[p] \\ p = \bar{p}_0 \end{cases}$$

The Wasserstein gradient flow of the entropy functional $J[p] = \int_{\Omega} p \log p dx$ is the heat equation with Neumann boundary conditions

$$\begin{cases} \partial_t p = -\text{grad}_{W_2} J[p] = \Delta p & \text{in } \Omega \\ \partial_n p = 0 & \text{on } \partial\Omega \end{cases}$$

If $J[p] = \frac{1}{m+1} \int_{\Omega} p^{m+1}$ for $m+1$ with $m > 0$, then the gradient flow

$$\text{is } \begin{cases} \partial_t p = -\text{grad}_{W_2} J[p] = \Delta(p^m) & \text{in } \Omega \\ \partial_n(p^m) = 0 & \text{on } \partial\Omega \end{cases}$$

that is the porous medium eqⁿ if $m > 1$ or the fast diffusion equation (if $m \in (0, 1)$)

(3)